

# Neural Model Checking

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# Intro

- **LTL verification** with proof certificates
- proof certificates represented as **Neural Networks**
- verification done on hardware designs
- unsupervised / sound / practical

# Some Notations

- $X_{\mathcal{M}}$  : set of (bit-vector) variables
  - $\text{reg } X_{\mathcal{M}} \subseteq X_{\mathcal{M}}$  : register variables
  - $\text{inp } X_{\mathcal{M}} \subseteq X_{\mathcal{M}}$  : input variables
- $\text{obs } X_{\mathcal{M}} \subseteq X_{\mathcal{M}}$  : observable variables for atomic props in LTL
- $\text{Update}_{\mathcal{M}}$  : relation over  $X_{\mathcal{M}}$  and  $\text{reg } X'_{\mathcal{M}}$
- $\mathbf{s} \in S$  : state (valuation over  $X_{\mathcal{M}}$ )

# Recall: Automata-Theoretic LTL MC

- how to check  $\mathcal{M} \models \Phi$  ?
- 1) build an NBA for  $\mathcal{M} \parallel \mathcal{A}_{\neg\Phi}$ 
  - states of this NBA:  $(s, q)$
- 2) check if final (or fair) states in  $F$  can be visited **i.o.**
  - can  $\rightarrow$  return false (+ counterexample: lasso)
  - cannot  $\rightarrow$  return true (+ **proof certificate: ranking function**)

# Ranking Functions as Proofs

A ranking function takes a state of the **synchronous product** as input, and outputs a rank

i.e. ranking function  $V: \text{reg } S \times Q \rightarrow R$  where  $(R, \prec)$ : well-founded

★ Conditions for ranking functions:

$$(s, q) \rightarrow_{\mathcal{M} \parallel \mathcal{A}_{\neg \Phi}} (s', q') \implies V(\text{reg } s, q) \succeq V(\text{reg } s', q') \quad (1)$$

$$(s, q) \rightarrow_{\mathcal{M} \parallel \mathcal{A}_{\neg \Phi}} (s', q') \wedge q \in F \implies V(\text{reg } s, q) \succ V(\text{reg } s', q') \quad (2)$$

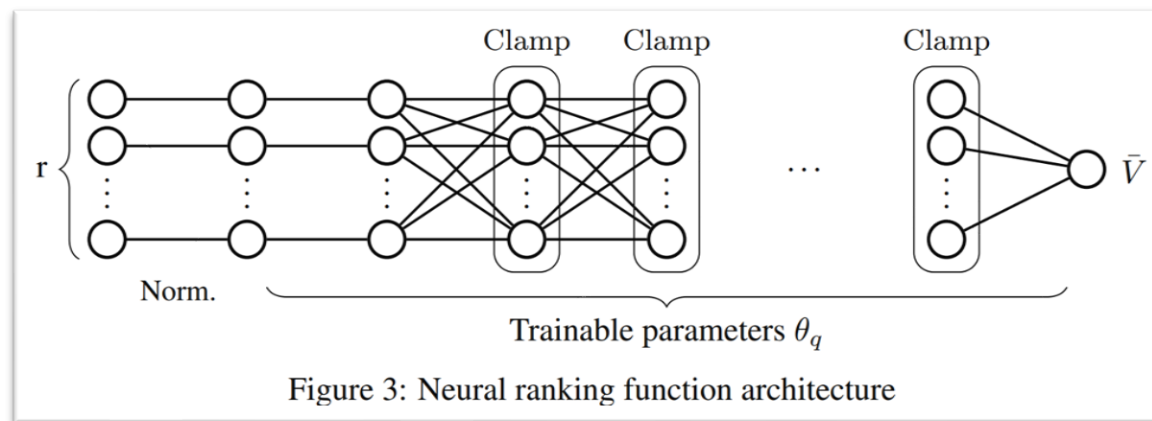
# Ranking Functions as NN's

Ranking functions are represented by neural networks:

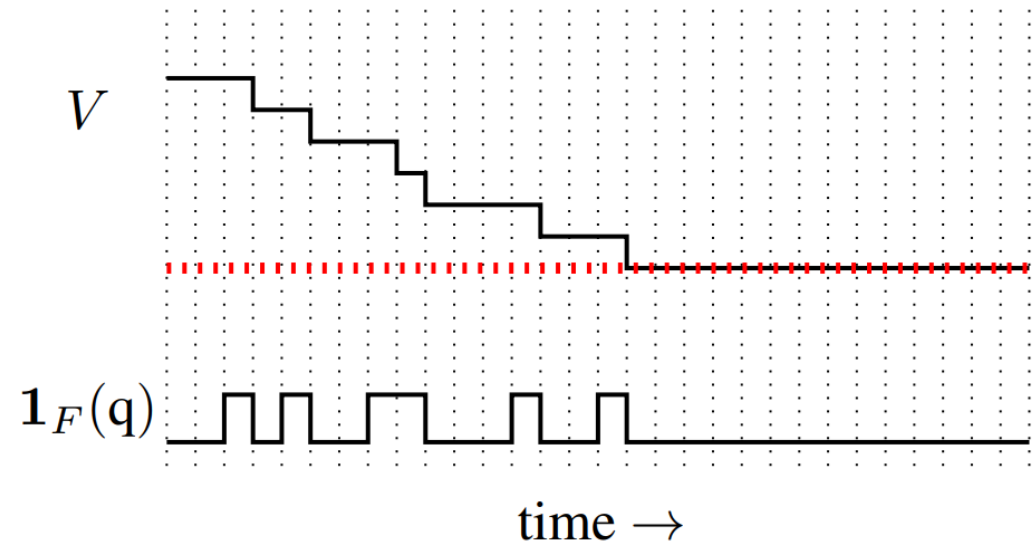
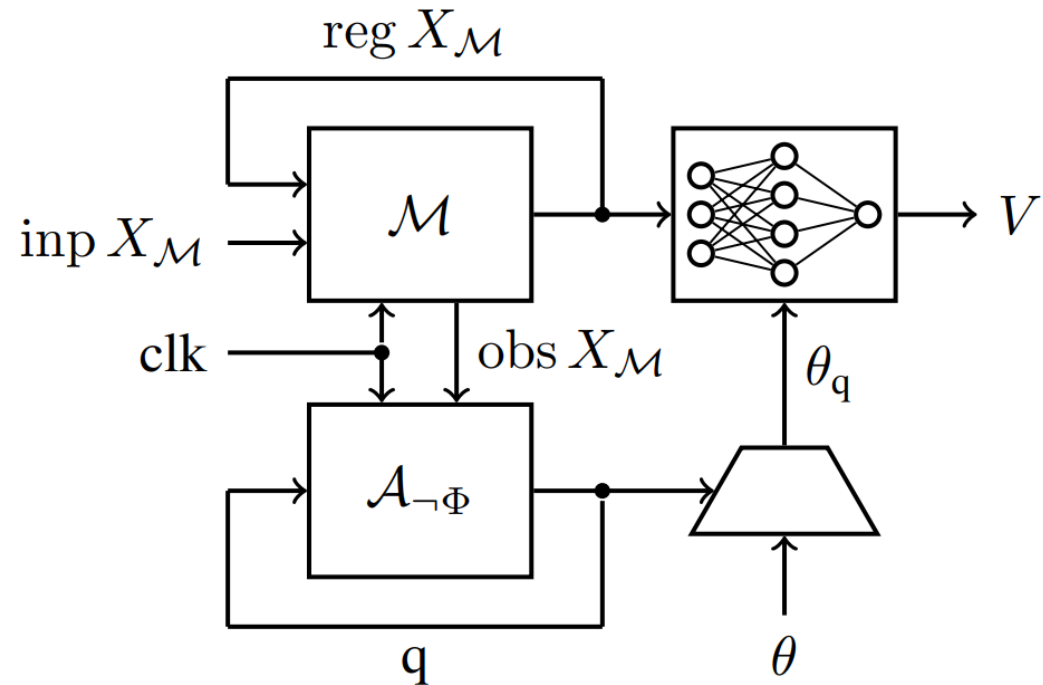
$$V(r, q) \equiv \bar{V}(r; \theta_q)$$

where,

- $\bar{V}: \mathbb{R}^n \times \Theta \rightarrow \mathbb{R}$
- $n = |\text{reg } X_{\mathcal{M}}|$

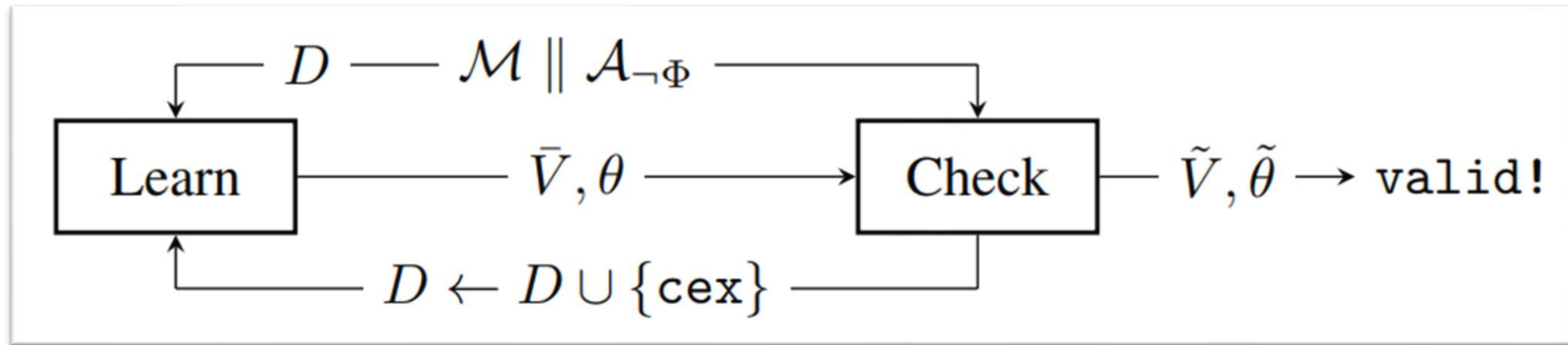


# Synchronous Products & Ranking Functions



# ★ Learn-and-Check Procedure

Task: verify  $L_{\mathcal{M}} \subseteq L_{\Phi}$





# Learning

To train  $\bar{V}$ , for each quadruple  $(\mathbf{r}, \mathbf{q}, \mathbf{r}', \mathbf{q}') \in D$ , minimize the following:

$$\mathcal{L}_{\text{Rank}}(\mathbf{r}, \mathbf{q}, \mathbf{r}', \mathbf{q}'; \theta) = \text{ReLU}(\bar{V}(\mathbf{r}'; \theta_{\mathbf{q}'} - \bar{V}(\mathbf{r}; \theta_{\mathbf{q}}) + \epsilon \cdot \mathbf{1}_F(\mathbf{q})).$$

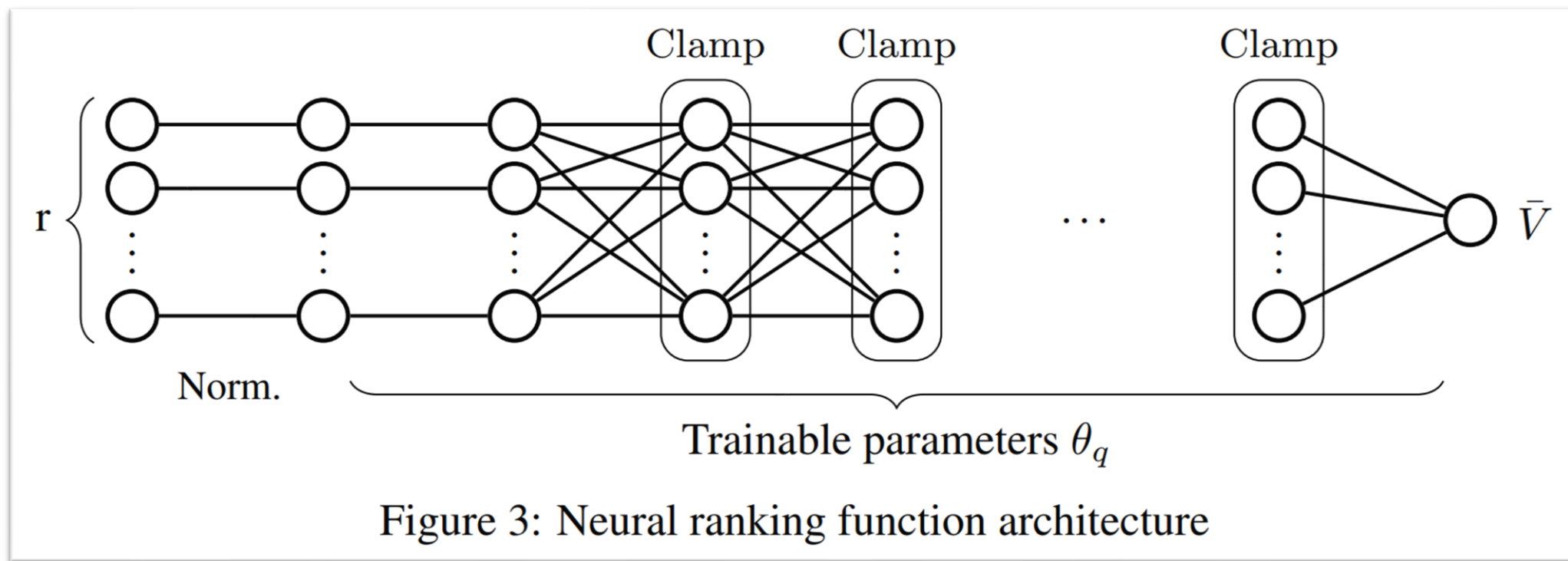
Suppose loss = 0.

- if  $\mathbf{q} \notin F$ ,  $\bar{V}(\mathbf{r}; \theta_{\mathbf{q}}) \geq \bar{V}(\mathbf{r}'; \theta_{\mathbf{q}'})$
- if  $\mathbf{q} \in F$ ,  $\bar{V}(\mathbf{r}; \theta_{\mathbf{q}}) \geq \bar{V}(\mathbf{r}'; \theta_{\mathbf{q}'} + \epsilon$

Overall, the training ensures the following total loss function to take **value zero**:

$$\mathcal{L}(D; \theta) = \mathbb{E}_{(\mathbf{r}, \mathbf{q}, \mathbf{r}', \mathbf{q}') \in D} [\mathcal{L}_{\text{Rank}}(\mathbf{r}, \mathbf{q}, \mathbf{r}', \mathbf{q}'; \theta)]$$

# Learning



$$\text{Clamp}(x; u) = \max(0, \min(x, u))$$

# Learning

- Suppose training resulted in *zero* loss
- What do we have?
- Conditions (1) & (2) hold for the dataset  $D$
- But not necessarily for *any* transitions in  $\rightarrow_{\mathcal{M} \parallel \mathcal{A} \neg \Phi}$
- So we need the “checking” phase

# Checking

(For efficiency reasons, ranking functions are quantized as integers)

$$\bigvee_{q, q' \in Q} \text{Update}_{\mathcal{M} \parallel \mathcal{A}_{\neg \Phi}}(s, q, r', q') \wedge \tilde{V}(\text{reg } s; \tilde{\theta}_q) - \mathbf{1}_F(q) < \tilde{V}(r'; \tilde{\theta}_{q'})$$



a satisfying assignment  
 $s \in S, r' \in \text{reg } S$

UNSAT  
(verified)

# Evaluation

Table 1: Number of verification task completed by academic and industrial tool, per design

	LS	LCD	Tmcp	i2cS	7-Seg	PWM	VGA	UARTt	Delay	Gray	Total
Tasks	16	14	17	20	30	12	10	10	32	33	194
ABC	2	3	7	3	8	2	3	<b>10</b>	6	13	57
nuXmv	8	9	12	10	10	7	3	<b>10</b>	24	24	117
→ our	15	<b>14</b>	<b>17</b>	<b>18</b>	<b>30</b>	11	0	<b>10</b>	<b>32</b>	<b>33</b>	180
Ind. X	<b>16</b>	<b>14</b>	<b>17</b>	<b>18</b>	18	<b>12</b>	<b>10</b>	<b>10</b>	19	22	156
Ind. Y	0	0	0	0	0	0	0	0	0	0	0

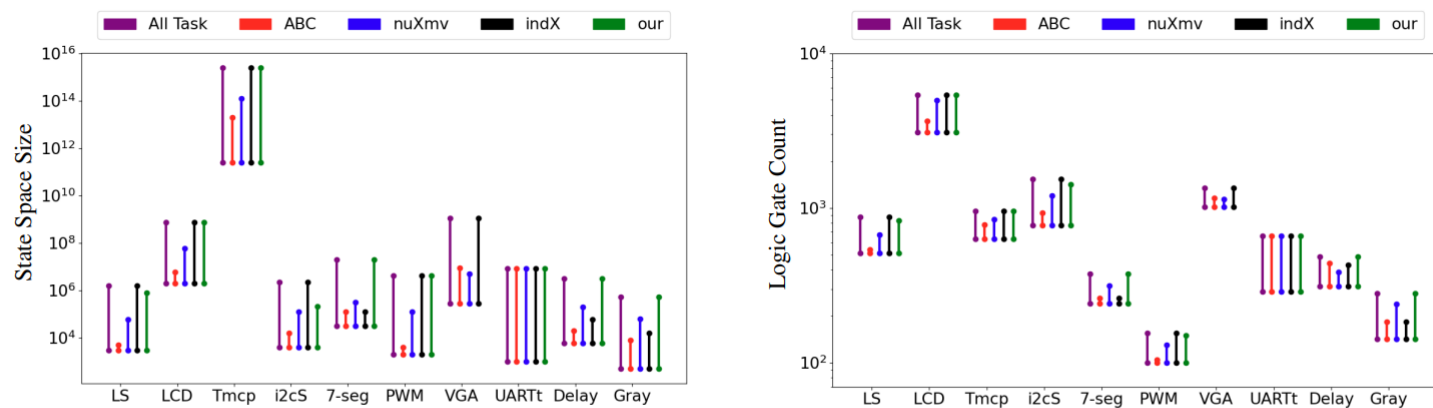


Figure 5: Solved tasks in terms of state space size and logic gate count (log scale)

\* timeout = 5h